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Patent
Attorney Docket No. 033808-010

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Patent Application of

Dong-ryeol Park et al.

Group Art Unit: 2877

Application No.: 10/753,403

Examiner: Unassigned

Filing Date: January 9, 2004

Confirmation No.: 6389

Title: MOBILE ROBOT, AND SYSTEM AND METHOD FOR AUTONOMOUS NAVIGATION OF THE SAME

REQUEST FOR CORRECTED OFFICIAL FILING RECEIPT

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Sir:

Enclosed is a copy of the Official Filing Receipt marked in red to show correction/corrections that is/are needed. The correction/corrections is/are as follows:

In the Title, please delete "autnomous"; and insert therefor --autonomous--.

Issuance of a corrected Official Filing Receipt is respectfully requested.

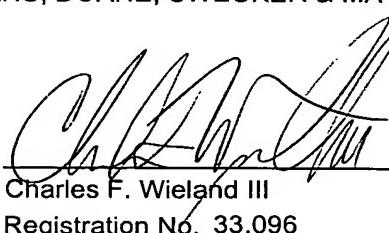
Respectfully submitted,

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Date: July 26, 2004

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APPL NO.	FILING OR 371 (c) DATE	ART UNIT	FIL FEE REC'D	ATTY.DOCKET NO	DRAWINGS	TOT CLMS	IND CLMS
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CONFIRMATION NO. 6389
 UPDATED FILING RECEIPT

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Date Mailed: 07/06/2004

Receipt is acknowledged of this regular Patent Application. It will be considered in its order and you will be notified as to the results of the examination. Be sure to provide the U.S. APPLICATION NUMBER, FILING DATE, NAME OF APPLICANT, and TITLE OF INVENTION when inquiring about this application. Fees transmitted by check or draft are subject to collection. Please verify the accuracy of the data presented on this receipt. If an error is noted on this Filing Receipt, please write to the Office of Initial Patent Examination's Filing Receipt Corrections, facsimile number 703-746-9195. Please provide a copy of this Filing Receipt with the changes noted thereon. If you received a "Notice to File Missing Parts" for this application, please submit any corrections to this Filing Receipt with your reply to the Notice. When the USPTO processes the reply to the Notice, the USPTO will generate another Filing Receipt incorporating the requested corrections (if appropriate).

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Assignment For Published Patent Application

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Domestic Priority data as claimed by applicant

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Title

AUTONOMOUS

Mobile robot, and system and method for ~~autonomous~~ navigation of the same

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